S.A. Malliaroudakis Maritime UK Ltd.

# **NOON REPORTER SOFTWARE**

## **BRIEF DESCRIPTION**

The electronic reporting templates (ie. noon reports, COSP, EOSP, Inbound, Inport, Outbound, Stoppage, etc.) ensure seamless input of necessary variables/parameters, providing simultaneously restrictions and guidance for correct and reasonable relevant values (ie. RPM, Speed, Position, Weather Data, etc.).

Ship Reporter (Electronic Reporting Templates) addresses to collect data at the right time and to check consistency of all data entered.

The purpose of Ship Reporter is to reduce the number of reporting systems currently in use in order to ease the workload on the crews, and to have more accurate and value-adding data.

In future, vessels will have only one point of entry for reporting which is meant to ensure a higher level of certainty in our prognoses, which again will enable proper corrective actions carried out at the right time.

#### Features & Benefits of this Module for vessel and office application:

- Ease of use.
- Tailored to Company's Reporting Policy.
- Good Data Quality of reports.
- Minimization of human errors to vessel's reporting due to ship-specific limits and standardization of typing/wording.
- Easy transmission of reported data for further processing as well as for assessment of Voyage Performance and compliance to new regulations (ie. MRV).
- Simple generation of automatic email with all the required data for easy reporting to all the concerned parties.
- Smooth and care free integration of the stored data to third party software products.
- Consistent records of reported data that can be retrieved for any period.
- Allowance of monitoring historic reported data with statistical analysis and KPIs integrations (ie. EEOI, Fuel Benchmarking).
- Uniformity of reporting method.

# FREQUENTLY ASKED QUESTIONS

- 1. How the crew familiarization is achieved?
  - a. Manual is incorporated in each Program with detailed & extensive Instructions
  - b. Distant Training
  - c. Direct Replies to Email of Masters / Chief Officers / Chief Engineers with Cc to your good Company
  - d. User Friendliness of Software Interface with a brief description of required actions
- 2. How we can we handle tiresome ISM / SMS Amendments for alignment with this SMM Product?
  - a. SMM Software is tailored to your company's policy/S.M.S. meaning minor ISM/SMS alterations.
  - Just a quick reference to the SMM Software in place and their Manual Contents in ISM is, often, common and effective practice for the majority Shipping Companies.
- 3. Relative requirements of Programs (hardware, software, data exchange if any)
  - a. Light, server-based application running exclusively on Windows operating system environments
  - b. SMM Software can be operated by multiple users (clients) on a network
  - c. Sync Mechanism requires email access or *data import path* for the whole fleet or a desired path for each vessel.
  - d. Possible export in desired editable format, upon discussion and analysis.

### SCREENSHOTS

#### Please see below Screenshots:

Save Report View Form View	Report Print Report	Send Report	Login User:	Demo Userdemo (CHIEF ENGINEER	() Close
DEMO Ship Management I	nc.			Noon Report	
Main Information Vessel Name: M/V DEMO		IMO Number: 1	9296743	Call Sign: DUGR	
Date*		Longitude*	•	UTC Time Offset*	+E,-W)
	Enter numeric v	values: 0 - 90 for the degrees(xx		· · · · · · · · · · · · · · · · · · ·	·e,-w)
- Voyage Information	Enter numeric s	values: 0 - 90 for the degrees(xx		· · · · · · · · · · · · · · · · · · ·	-2,-11)
	Enter numeric v			· · · · · · · · · · · · · · · · · · ·	-е,- м)
Voyage Information Voyage Number*		values: 0 - 90 for the degrees(xx: Master*	x) of Position Latitu	ide	
Voyage Information Voyage Number* Instructed Speed Basis*		values: 0 - 90 for the degrees(xx Master* Loading Condition*	x) of Position Latitu	Ballast Water ROB	MT
Voyage Information Voyage Number* Instructed Speed Basis* Instructed Speed	× KTs	Values: 0 - 90 for the degrees(xx Master* Loading Condition* Instructed RPM	x) of Position Latits	Ballast Water ROB	MT
Voyage Information Voyage Number* Instructed Speed Basis* Instructed Speed Avg Speed SLR*	× KTs KTs	Master* Loading Condition* Instructed RPM Calm Sea Speed	x) of Position Latitu	Ballast Water ROB Instructed Daily Cons Avg RPM SLR*	MT

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